

Ejercicio de repaso: considere un punto p en una variedad M. El plano tangente en p está dado por la ecuación

$$\vec{r} = u^1 \left(1, \frac{2}{3}\right) + u^2 \left(1, -\frac{2}{3}\right)$$

con u^1, u^2 parámetros del plano, que serán nuestras coordenadas. Calcule:

a) Los vectores base tangentes (base contravariante)

$$\vec{d}_1 = \frac{\partial \vec{r}}{\partial u^1} = \left(1, \frac{2}{3}\right)$$

$$\vec{d}_2 = \frac{\partial \vec{r}}{\partial u^2} = \left(1, -\frac{2}{3}\right)$$

b) Los covectores base (base covariante) $\vec{d}^1 = \vec{\nabla} u^1$, $\vec{d}^2 = \vec{\nabla} u^2$. Ocupamos $u^1(x, y)$, $u^2(x, y)$:

$$\begin{pmatrix} x \\ y \end{pmatrix} = u^1 \begin{pmatrix} 1 \\ \frac{2}{3} \end{pmatrix} + u^2 \begin{pmatrix} 1 \\ -\frac{2}{3} \end{pmatrix} \quad \mapsto \quad \begin{cases} u^1 = (2x+3y)/4 \\ u^2 = (2x-3y)/4 \end{cases}$$

$$\vec{d}^1 = \vec{\nabla} u^1 = \left(\frac{1}{2}, \frac{3}{4}\right)$$

$$\vec{d}^2 = \vec{\nabla} u^2 = \left(\frac{1}{2}, -\frac{3}{4}\right)$$

c) El vector $\vec{a} = a^1 \vec{d}_1 + a^2 \vec{d}_2 = \vec{d}_1 + \frac{4}{3} \vec{d}_2$ en la base covariante.

Resolvemos el sist. de ec: $\vec{d}_1 + \frac{4}{3} \vec{d}_2 = a_1 \vec{d}^1 + a_2 \vec{d}^2$, insertando los vectores numéricos

$$\mapsto \begin{cases} a_1 = 59/27 \\ a_2 = 67/27 \end{cases}$$

d) La norma

$$|\vec{a}|^2 = a^i a_i = \dots = \frac{145}{81}$$

e) El tensor métrico

$$(g_{ij}) = \begin{pmatrix} \vec{d}_1 \cdot \vec{d}_1 & \vec{d}_1 \cdot \vec{d}_2 \\ \vec{d}_2 \cdot \vec{d}_1 & \vec{d}_2 \cdot \vec{d}_2 \end{pmatrix} = \begin{pmatrix} \frac{13}{9} & \frac{5}{9} \\ \frac{5}{9} & \frac{13}{9} \end{pmatrix}$$

$$\text{vamos: } a_i = g_{ij} a^j$$

$$\begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = \begin{pmatrix} \frac{13}{9} & \frac{5}{9} \\ \frac{5}{9} & \frac{13}{9} \end{pmatrix} \begin{pmatrix} 1 \\ 4/3 \end{pmatrix} = \begin{pmatrix} \frac{13}{9} + \frac{5}{9} \cdot \frac{4}{3} \\ \frac{5}{9} + \frac{13}{9} \cdot \frac{4}{3} \end{pmatrix} = \begin{pmatrix} \frac{59}{27} \\ \frac{67}{27} \end{pmatrix} \quad \checkmark$$

Problema: sean las siguientes 1 formas en el espacio $\Lambda^1 L$:

$$a = a_1 \sigma_1 + a_2 \sigma_2 \quad b = b_1 \sigma_1 + b_2 \sigma_2$$

Demuestre que al hacer $a \wedge b$ queda el determinante de la matriz

$$\begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix}$$

$$a \wedge b = (a_1 \sigma_1 + a_2 \sigma_2) \wedge (b_1 \sigma_1 + b_2 \sigma_2)$$

$$= a_1 b_1 \cancel{\sigma_1 \wedge \sigma_1} + a_1 b_2 \sigma_1 \wedge \sigma_2 + a_2 b_1 \sigma_2 \wedge \sigma_1 + a_2 b_2 \cancel{\sigma_2 \wedge \sigma_2}$$

$$= a_1 b_2 \sigma_1 \wedge \sigma_2 + a_2 b_1 \sigma_2 \wedge \sigma_1$$

$$= (a_1 b_2 - a_2 b_1) \sigma_1 \wedge \sigma_2$$

Problema: Calcule el producto cuña entre un elemento $\alpha \in \Lambda^1 L$ y otro $\beta \in \Lambda^2 L$

y demuestre que se obtiene un elemento de $\Lambda^3 L$ cuya componente es el producto punto

donde las componentes de α son a_i , y las de β son b_i .

$$\alpha = a_1 dx_1 + a_2 dx_2 + a_3 dx_3$$

$$\beta = b_1 dx_2 \wedge dx_3 + b_2 dx_3 \wedge dx_1 + b_3 dx_1 \wedge dx_2$$

$$\alpha \wedge \beta = (a_1 dx_1 + a_2 dx_2 + a_3 dx_3) \wedge (b_1 dx_2 \wedge dx_3 + b_2 dx_3 \wedge dx_1 + b_3 dx_1 \wedge dx_2)$$

$$= a_1 b_1 dx_1 \wedge dx_2 \wedge dx_3 + a_2 b_2 dx_2 \wedge dx_3 \wedge dx_1 + a_3 b_3 dx_3 \wedge dx_1 \wedge dx_2$$

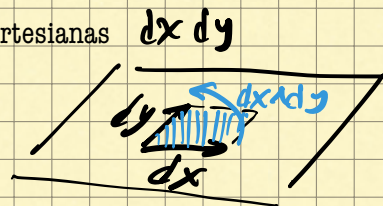
$$= (a_1 b_1 + a_2 b_2 + a_3 b_3) dx_1 \wedge dx_2 \wedge dx_3.$$

Problema: utilizando formas diferenciales, transforme el diferencial de área en coordenadas cartesianas a un diferencial de área en coordenadas polares

$$\begin{aligned} x &= r \cos \varphi \Rightarrow dx = \cos \varphi dr - r \sin \varphi d\varphi \\ y &= r \sin \varphi \Rightarrow dy = \sin \varphi dr + r \cos \varphi d\varphi \end{aligned}$$

$$dx \wedge dy = (\cos \varphi dr - r \sin \varphi d\varphi) \wedge (\sin \varphi dr + r \cos \varphi d\varphi)$$

$$= (r \cos^2 \varphi dr \wedge d\varphi - r^2 \sin \varphi d\varphi \wedge dr) = r dr \wedge d\varphi$$



$f(x, y) : \rightarrow \text{zero-form}$

Legendre transforms

$$df(x, y) = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy$$

$$df = \underbrace{u}_{u(x, y)} dx + \underbrace{v}_{v(x, y)} dy : \text{diff form (1-form) expressed in the basis } (dx, dy)$$

$$g(u, y) = f(x, y) - ux : \rightarrow \text{zero-form}$$

$$dg(u, y) = df(x, y) - d(ux) \rightarrow \text{1 form}$$

u is $u(x, y)$, so,

$$= df(x, y) - x du(x, y) - u(x, y) dx$$

$$= \underline{u(x, y) dx} + v(x, y) dy - x du(x, y) - \underline{u(x, y) dx}$$

$$dg(u, y) = v(x, y) dy - x du(x, y)$$

but because we want g to be function of u, y only

$$\text{and } dg(u, y) = \frac{\partial g}{\partial u} du + \frac{\partial g}{\partial y} dy$$

we must have

$$-\frac{\partial g}{\partial y} = x ; \quad \frac{\partial g}{\partial y} = v(x, y)$$

in order to eliminate x .

• let $x \rightarrow \dot{q}$, $y \rightarrow q$

$$f(x, y) \rightarrow L(q, \dot{q})$$

$$u \rightarrow p, \quad g(u, y) \rightarrow H(p, q)$$

$\rightarrow$ Legendre transf. from mechanics

$$H(p, q) = L(q, \dot{q}) - p \dot{q}$$

• Let $x \rightarrow V$, $y \rightarrow S$

$$f(x, y) \rightarrow U(S, V)$$

$$u \rightarrow -p, \quad g(u, y) \rightarrow H(S, p)$$

$\rightarrow$ Legendre transf. from thermodyn.

$$H(S, p) = \underbrace{U(S, V)}_{\text{internal energy}} + \underbrace{Vp}_{\text{enthalpy}}$$

Ex 1 Imagine a 3D vector space L with 3 basis dx_1, dx_2, dx_3 .

a) Compute the gen. form of all possible p-forms.

b) compute $\underline{a} \wedge \underline{b}$ in that basis.

a) $\bigwedge^0 L = \mathbb{R} : a \quad (\text{scalar})$

$\bigwedge^1 L = L : a_1 dx_1 + a_2 dx_2 + a_3 dx_3 \quad (1\text{-form})$

$\bigwedge^2 L : a_{12} dx_1 \wedge dx_2 + a_{23} dx_2 \wedge dx_3 + a_{31} dx_3 \wedge dx_1$

$\bigwedge^3 L : a_{123} dx_1 \wedge dx_2 \wedge dx_3$

there are no more possible $\bigwedge^p L$.

b) $(a_1 dx_1 + a_2 dx_2 + a_3 dx_3) \wedge (b_1 dx_1 + b_2 dx_2 + b_3 dx_3)$

$$= a_1 b_2 dx_1 \wedge dx_2 + a_1 b_3 dx_1 \wedge dx_3$$

$$+ a_2 b_1 dx_2 \wedge dx_1 + a_2 b_3 dx_2 \wedge dx_3$$

$$+ a_3 b_1 dx_3 \wedge dx_1 + a_3 b_2 dx_3 \wedge dx_2$$

$$= (a_1 b_2 - a_2 b_1) dx_1 \wedge dx_2 + (a_2 b_3 - a_3 b_2) dx_2 \wedge dx_3 + (a_3 b_1 - a_1 b_3) dx_3 \wedge dx_1$$

$\underline{a \times b} !$

$\mathbb{R}^3 \rightarrow$ Compute $d(dx \wedge dy) = \underbrace{d(dx)}_{\text{rules} \Rightarrow 0} \wedge dy - dx \wedge \underbrace{d(dy)}_{\text{rules} \Rightarrow 0}$.

Problema: demuestre que $d(df) = 0$.

Considere $f \in \Lambda^0 L$, $f(x, y, z)$

$$\Rightarrow df = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy + \frac{\partial f}{\partial z} dz \in \Lambda^1 L$$

$$\begin{aligned} \Rightarrow d(df) &= d\left(\frac{\partial f}{\partial x} dx\right) + d\left(\frac{\partial f}{\partial y} dy\right) + d\left(\frac{\partial f}{\partial z} dz\right) \\ &= \frac{\partial^2 f}{\partial x \partial x} \cancel{dx \wedge dx}^0 + \frac{\partial^2 f}{\partial y \partial x} dy \wedge dx + \frac{\partial^2 f}{\partial z \partial x} dz \wedge dx \\ &\quad + \frac{\partial^2 f}{\partial x \partial y} dx \wedge dy + \frac{\partial^2 f}{\partial y \partial y} dy \wedge dy + \frac{\partial^2 f}{\partial z \partial y} dz \wedge dy \\ &\quad + \frac{\partial^2 f}{\partial x \partial z} dx \wedge dz + \frac{\partial^2 f}{\partial y \partial z} dy \wedge dz + \frac{\partial^2 f}{\partial z \partial z} dz \wedge dz^0 \end{aligned}$$

Si el orden de las derivadas es intercambiable, esto da cero.

Problema: demuestre que los coef. de $d(a_1 dx_1 + a_2 dx_2 + a_3 dx_3)$ dan $\vec{\nabla} \times \vec{a}$.

$$\begin{aligned} d(a_1 dx_1 + a_2 dx_2 + a_3 dx_3) &= \left(\frac{\partial a_3}{\partial x_2} - \frac{\partial a_2}{\partial x_3}\right) dx_2 \wedge dx_3 \\ &\quad + \left(\frac{\partial a_1}{\partial x_3} - \frac{\partial a_3}{\partial x_1}\right) dx_3 \wedge dx_1 \\ &\quad + \left(\frac{\partial a_2}{\partial x_1} - \frac{\partial a_1}{\partial x_2}\right) dx_1 \wedge dx_2 \end{aligned}$$

Problema: demuestre que $d(2\text{-forma})$ da los componentes de la divergencia.

$$\begin{aligned} d(a_{23} dx_2 \wedge dx_3 + a_{31} dx_3 \wedge dx_1 + a_{12} dx_1 \wedge dx_2) \\ = \left(\frac{\partial a_{23}}{\partial x_1} + \frac{\partial a_{31}}{\partial x_2} + \frac{\partial a_{12}}{\partial x_3}\right) dx_1 \wedge dx_2 \wedge dx_3 \end{aligned}$$